

Time	Monday	Tuesday	Wednesday	Thursday	Friday
07:30–08:45	Breakfast	Breakfast	Breakfast	Breakfast	Breakfast
09:00–10:30	Intro Individual intros Breakout topics	Breakout reports Resampling topics Emily Collins: Where's the Trust? The Implications of Human Interactions for Trustworthy Robotics and AI	Breakout reports Gabriele Roger: Introduction to Automated planning	Resampling topics Alberto Speranzon: On the latent space structure of some deep neural network models Mak Roberts: Hierarchical Goal Networks: A Primer and Recent Results	Breakout reports Breakout session
10:30–11:00	Break	Break	Break	Break	Break
11:00–12:15	Breakout voting Individual intros Jyotirmoy Deshmukh: How do we assess if an AI model has learned to reason?	Sanjit Seshia: Formal Specification for AI-Enabled Autonomy Martin Törngren: A Systemic Perspective when Assessing AI-based CPS	Malte Helmert: Certifying algorithms for automated planning Sterre Lutz: Neural Certificates for Control Systems	Ruzica Piskac and Scott Shapiro: Using AI and Formal Methods for Legal Reasoning Hanna Kurniawati: POMDPs: Where are we? + Its use for User-Friendly Assessment of Robotics Systems	Report-outs and write-ups
12:15–14:00	Lunch	Lunch	Lunch	Lunch	Lunch
14:00–15:30	Individual intros Houssam Abbas: Logic-based normative AI and the shortcomings of statistical value alignment.	Reid Simmons: Explaining Agent Models Sarah Keren: Encouraging Autonomous Agents to Behave Nicely	Post-lunch excursion	Pulkit Verma: When Robots Come Home: Who Models Safety in Personal Robotics? Short Talks: Bishwamitra Ghosh, Nakul Gopalan, Till Hofmann	—
15:30–16:00	Coffee	Coffee		Coffee	—
16:00–17:30	Breakout session	Breakout session		Breakout session	—
18:00	Dinner	Dinner	Dinner	Dinner	